

---

## A SYSTEMS ENGINEERING TOOL FOR FMS PLANNING

By

MAJOR ROBERT E. SCHAFRIK, USAF

The Department of Defense plays a major role in executing national policy when it makes a commitment to sell a weapon system to a country. But such sales are becoming increasingly complex due to interaction and inter-relationships between the U.S. Government agencies, U.S. contractors, foreign government agencies, and foreign contractors. This high degree of complexity is particularly true in those programs involving coproduction, such as the F-16 fighter aircraft.

The F-16 program was established as a consortium effort between the U.S. and four European partners (referred to as the European Participating Governments or EPGs -- Belgium, Denmark, The Netherlands, and Norway). The agreement provided for European Coproduction of 58 percent of the procurement value of their own aircraft for the original 348 EPG F-16 buy, and 15 percent of all third country sales. In addition, several third countries themselves have requested coproduction. Also, some third countries have requested delivery of F-16s well short of normal lead times.

Thus, in such a dynamic, multi-dimensional, and multi-relational program the FMS (Foreign Military Sales) manager's job can become extremely complex. Anticipating and forestalling problems, establishing and maintaining key interfaces, responding to program changes, planning for future programs, etc., usually require information and understanding about the program by many levels of managers. Since this rarely occurs, program management rarely functions smoothly in responding to new inputs. Also, personnel turn-over, an unavoidable fact of life, typically wipes out corporate memory, resulting in the loss of important information.

This paper describes a systems engineering tool, called Function Modeling, which can very effectively assist overcoming the problem areas which programs like the F-16 typically encounter. It should be emphasized that this

tool is not a replacement for good management. It does provide managers with an approach to help them solve very difficult problems of understanding the relationships between the many different activities and information users which occur in a program.

The Function Model is essentially a graphical technique for representing the activities (or functions) of the system (The FMS program) which the manager deems important. The basic rules and definitions of the technique are summarized in the Appendix. (It is recommended that the Appendix be read before proceeding). Note that this model deals with inter-relationships between activities and does not take into account the time required to accomplish the activity. Thus, it compliments other well known systems engineering tools, such as Gant charts and Critical Path Networks.

The remainder of this paper will describe an application of the Function Model to the FMS sale to Pakistan (Peace Gate). This program required delivery and operation of the first six F-16s in Pakistan within 12 months of the signing of the LOA. Normal lead time is 42 months. The fact that this was accomplished on schedule without adverse impact to the USAF F-16 program speaks well for the management of the program. The model which follows is an attempt to convey to managers who did not participate in the Peace Gate program some examples of what was learned in the crucible of a high interest, accelerated program.

The Peace Gate program involved initial delivery of six F-16s and base activation in Pakistan within 12 months of LOA signature and delivery of 34 aircraft within normal lead time. Figure 1 is a high level graphical model of the Peace Gate program. Figure 2 is a subdivision of the activity shown in Figure 1. Table I contains the high level node tree for the program. Note that Figure 1 is a graphical representation of activity  $A_0$ , and Figure 2 shows the inter-relationship between activities  $A_1$ ,  $A_2$ ,  $A_3$ , and  $A_4$ .

The Program Management Plan (PMP) is an extremely important document. It specifically states who is responsible for what. The process used to create the PMP is also important, since, during the process of proposing the plan, the participants gain an understanding of what and how they will

accomplish their tasks and who they need to interact with. Table II is a Node Tree developing the A24 activity, "Create Program Management Plan." Figure 3 is the graphical representation of the A24231124 Activity (or Node), "Assign Propulsion SPO Tasks."

These illustrations of the Function Model, derived from one experience with the Peace Gate program, were meant to demonstrate the application of the model. In order to obtain the maximum utility from this concept, the A<sub>1</sub> through A<sub>4</sub> activities should be developed fully (i.e., to the lowest level of detail that provides meaningful data), and the model should not be the product of a single person or office, but integrate the comments from all interested parties. In this way, a complete, accurate model can be developed. Such a model could be useful in managing future FMS programs and in describing the FMS program for training purposes. It can provide a tool to organize the mountainous amount of information and activities generated for FMS programs.

## APPENDIX

The first step in constructing any model is to define the system. This is done by declaring what activity will be modeled. For example, an activity "Conduct an FMS Program" can be modeled provided the boundaries and restrictions of the system are specified. Thus, the purpose, viewpoint, and context of the model must be explicitly described.

The next step is preparation of the data. This is done by listing all the activities which are required to accomplish the activity being modeled. Personal knowledge, information from experts, consultation with reference material, etc., are all sources of this information. The activities are then grouped into logical sets. They will normally fall into a hierarchical pattern, so the next step is to arrange them that way. The principal activity being modeled is labeled  $A_0$ . A basic rule is that an activity cannot be further broken down (or "decomposed" as the systems analysts say) into more than six activities. Thus, the  $A_0$  activity (or "Node") can be broken down into  $A_1$  through  $A_6$ . Likewise,  $A_1$  can be broken down into  $A_{11}$  through  $A_{16}$ ;  $A_{11}$  can be broken down into  $A_{111}$  through  $A_{116}$ , etc. (Of course, an activity need not be broken down into 6 activities if fewer such activities are adequate.) The activity is described by an action verb with a subject. A listing of activities in hierarchical order is called a Node Tree. It is this Node Tree which serves as the building block for the model.

Each activity generally has information input into it and output from it. The activity changes the input information into the output information. By convention, the inputs are shown entering the activity box from the left and the output exiting the box to the right. Every activity must have at least one control. This control provides the required rules, performance criteria, and evaluation data by which the activity accomplishes its mission. In other words, the control serves as the executive. By convention, if an item is both an input and a control, it is only shown as a control. Thus, every activity must have a control and an output, but need not have an input. The controls are shown entering the activity box from the top.

Activities can accomplish their mission through the application of physical processes and equipment, called mechanisms. If it is useful to indicate the mechanisms on the model, they are shown entering the activity box from the bottom.

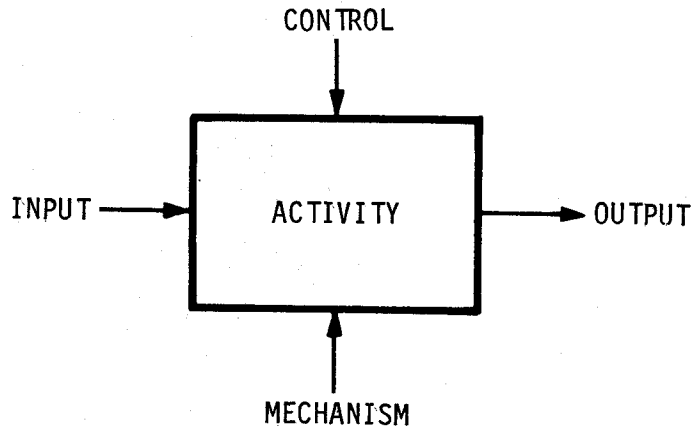
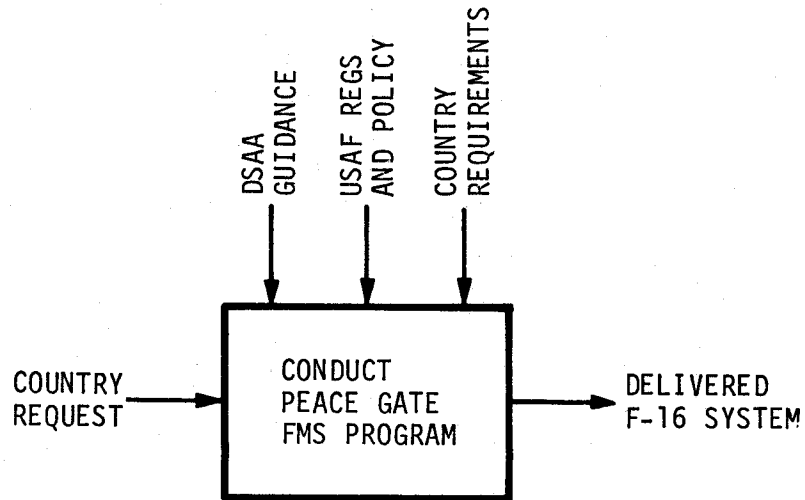
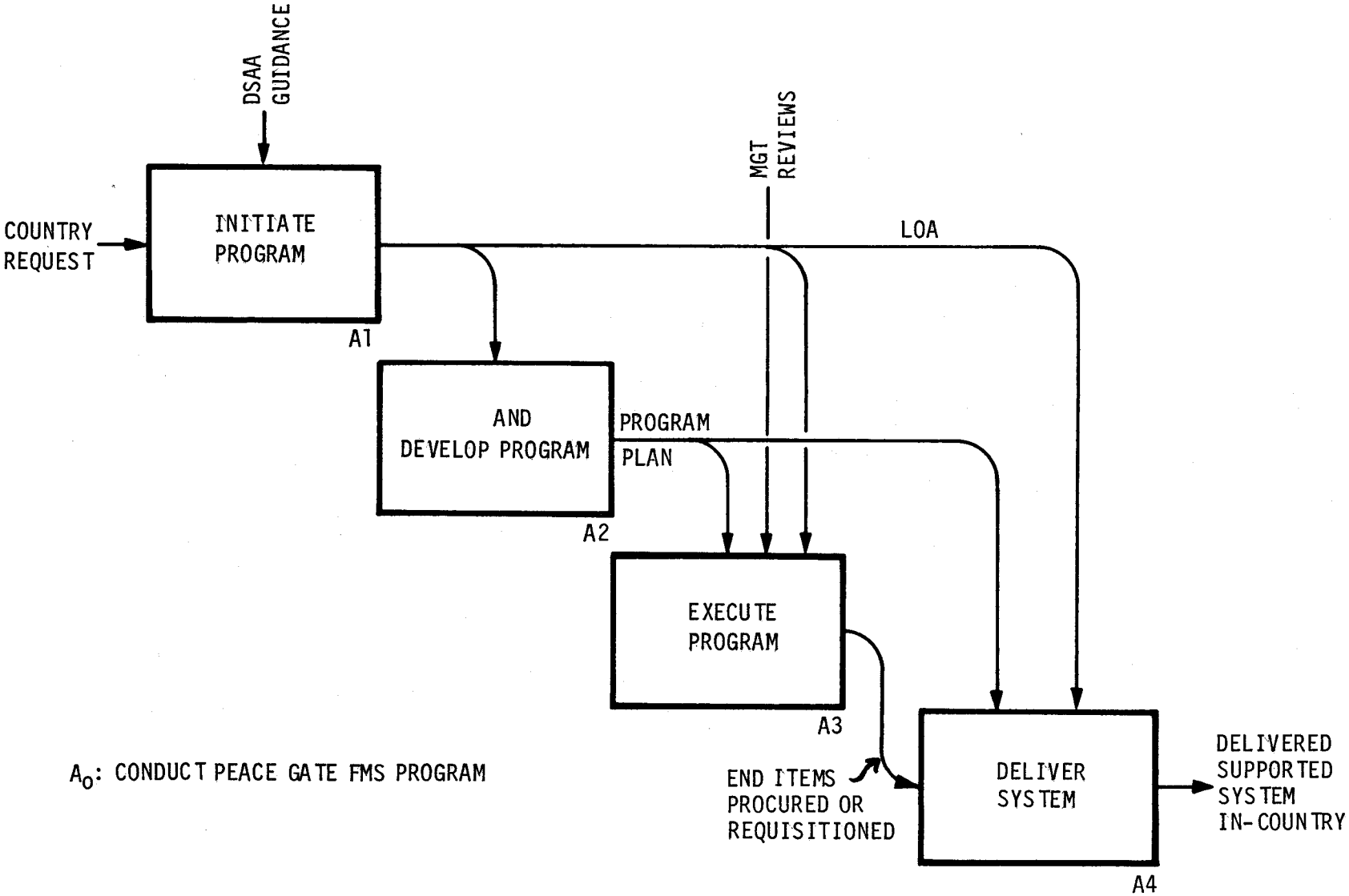


FIGURE 1



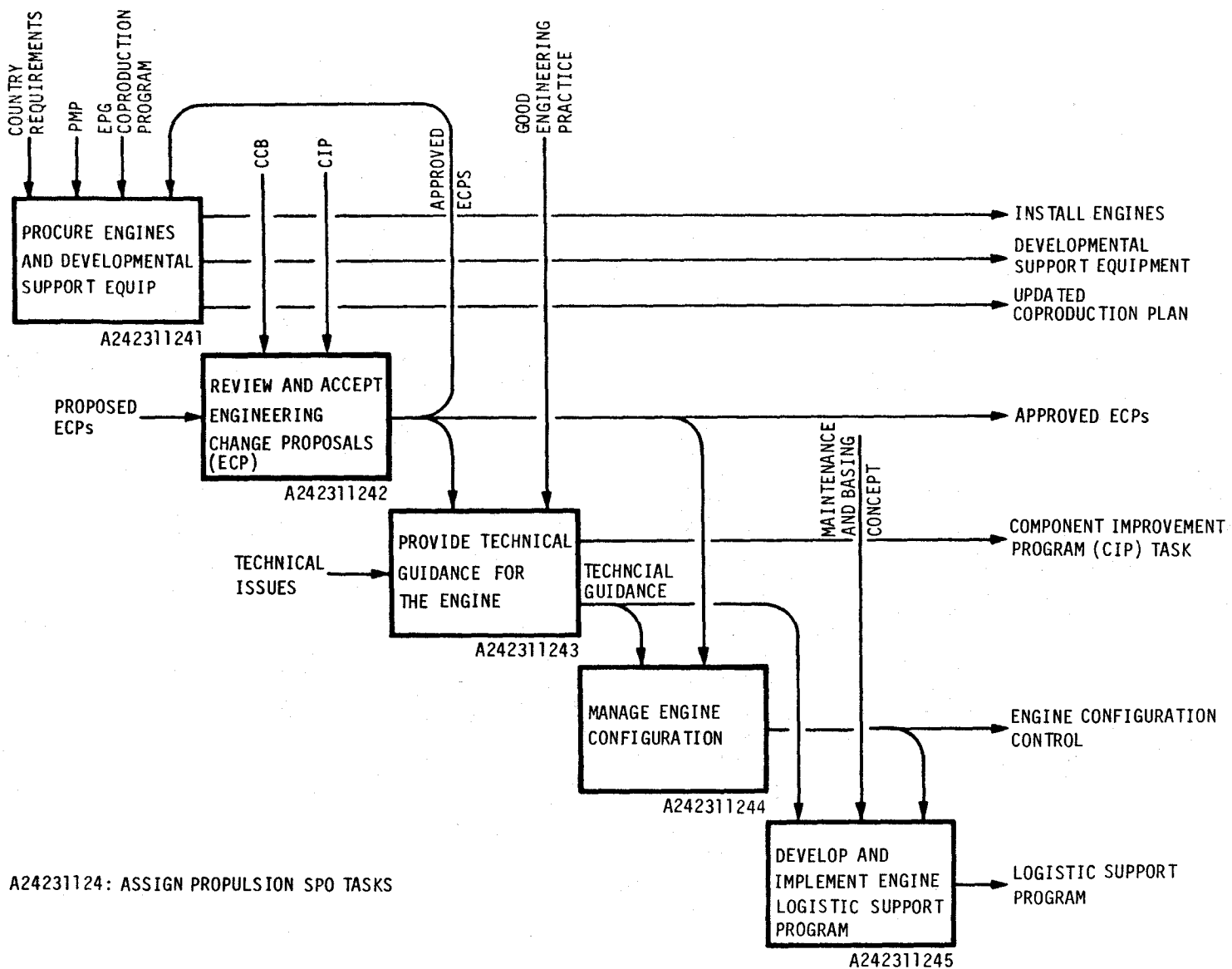
PURPOSE: DELINEATE THE FMS PROCESS  
VIEWPOINT: AIR STAFF PROGRAM MANAGER  
CONTEXT: USAF FMS PROGRAM

FIGURE 2



A<sub>0</sub>: CONDUCT PEACE GATE FMS PROGRAM

FIGURE 3



A24231124: ASSIGN PROPULSION SPO TASKS

TABLE I  
NODE TREE - OVERALL

AO: Conduct Peace Gate FMS Program

A1: Initiate Program

A11: Prepare P&R

A12: Process Letter of Request

A13: Prepare Pricing and Availability

A14: Perform Letter of Offer Processing and Presentation

A15: Issue Obligation Authority and Implementing Authority

A2: Define and Develop Plan

A21: Conduct Post Acceptance Review

A22: Establish Program Milestone

A23: Conduct Site Survey

A24: Create Program Management Plan

A25: Definitize Program Requirements

A3: Execute the Program

A31: Provide Integration

A32: Provide Procurement

A33: Provide Procurement for Engine

A34: Requisition and Ship Items

A35: Review Program Performance

A4: Delivery and Activate System

A41: Deliver System

A42: Activate Site

A43: Ferry Aircraft to Site

A44: Monitor Delivery of System

A45: Completion and Closure of Program

TABLE II

NODE TREE - CREATE PROGRAM MANAGEMENT PLAN

A24: Create Program Management Plan (PMP)

A241: Define Requirement

A242: Initiate Organizational Build Up for PMP

A2421: Delineate Required Tasks

A2422: Establish PMP Milestones

A2423: Assign Responsibilities

A24231: Differentiate Tasks

A242311: Assign Government Tasks

A2423111: Define Air Staff Tasks

A2423112: Define AFSC Tasks

A24231121: Definitize HQ Air Force System Command Tasks

A24231122: Assign F-16 SPO Tasks

A24231123: Assign Simulator SPO Tasks

A24231124: Assign Propulsion SPO Tasks

A242311241: Procure Engines and Developmental Support  
Equipment

A242311242: Review and Accept Engineering Change Proposals

A242311243: Provide Technical Guidance for the Engine

A242311244: Manage Engine Configuration

A242311245: Develop and Implement Engine Logistics Support  
Program

A24231125: Determine Other Tasks

A2423113: Define Tactical Air Command Tasks

A2423114: Define Air Training Command Tasks

A2423115: Define Air Force Logistic Command (AFLC) Tasks

A24231151: Definitize HQ AFLC Tasks

A24231152: Define AFLC International Logistic Center Tasks

A24231153: Assign Air Logistic Center (ALC) Tasks

A242311531: Define Ogden ALC Tasks

A242311532: Define San Antonio ALC Tasks

A242311533: Define Oklahoma City ALC Tasks

A242311534: Define Warner-Robbins ALC Tasks

A242311535: Define Aerospace Guidance and Metrology Center  
Tasks

A242312: Assign Contractor Tasks

A242313: Identify Country Tasks

- A24232: Establish Responsibilities
- A24233: Schedule Meetings for PMP Preparation
- A24234: Integrate Plan

A243: Prepare and Publish the PMP

- A2431: Evaluate Previous PMPs
- A2432: Collect Inputs
- A2433: Prepare Plan
- A2434: Publish and Distribute the PMP

A244: Utilize the PMP

A245: Update the PMP

## BIBLIOGRAPHY:

1. Robert E. Shannon, Systems Simulation: The Art and Science (Englewood Cliffs, NJ: Prentice-Hall, 1975), pp 1-33.
2. Larry Shpiner, Larry Warren, and Leo Bernier, Planning the Use of Robots, presented at the 15th National Technical Conference of the Society for the Advancement of Materials and Process Engineering (SAMPE), Oct 6, 1983, Mariott Inn, Cincinnati, Ohio.
3. William R. Synnott and William H. Gruber, Information Resource Management (New York, NY: John Wiley & Sons, 1981).
4. Integrated Computer-Aided Manufacturing Function Modeling Manual, Report UM 110231100, Contract F33615-78-C-5158, Materials Laboratory, AFWAL, Wright-Patterson Air Force Base, Ohio, 45433.

Major Robert Schafrik is Chief, F-16 Engine Programs, in the Tactical Engines Program Office, Deputy for Propulsion, Aeronautical Systems Division, Wright-Patterson AFB, OH. He holds a PhD in Metallurgical Engineering from Ohio State University and an MS in Aerospace Engineering from AFIT's School of Engineering. Previous assignments include Manager of the Air Force's Computer Aided Manufacturing Program, Chief of the Air Force Materials Lab Systems Acquisition Branch, basic research in high temperature materials, and Base Civil Engineer.